

X-G-RST-E Series User's Manual

High load motorized gimbals with built-in controllers and motor encoders

Selected currency: **US Doll**
All prices are displayed in **l**



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⚠ Heavy! Completely assembled X-G-RST-E Gimbals with crossmember plates for mounting the payload can weigh more than 15kg/33lb. Exercise caution when lifting/moving larger assemblies.

⚠ Tipping Hazard! Before mounting a payload or powering up the gimbal, ensure it is fully secured to a mounting surface. Moving the payload can cause unsecured gimbals to tip over, which may lead to injury or damage.

⚠ Pinch Hazard! Keep fingers and any loose objects (such as dangling cables) away from the elevation mounts whenever the device is moving or active as pinching could cause severe injury or cable damage.

💡 Important: Zaber's X-G-RST-E gimbals use X-RST-E rotary stages, which are capable of outputting high torque and supporting heavy centred loads. It is possible to damage the stage or reduce its lifetime under certain conditions within the limits of the torque and load ratings. Maximum angular momentum is also specified for this product to reduce the likelihood of shortened lifetime due to abrupt starts or stops of significant inertial loads. The distance of the payload crossmember plate to the elevation axis is adjustable. With increasing offset from the axis it is highly recommended to center the load with the elevation axis to achieve optimal gimbal performance and long lifetime.

Please see [Crossmember Height Adjustment](#) instructions for details.

💡 Important: When Adjusting the crossmember plate height, always ensure the crossmember plate feet fasteners are tight before engaging elevation axis apparatus. Regularly checking fasteners are tight is advised as small vibrations during gimbal operation can lead to loosening. Low-strength threadlocker such as Loctite 222 is recommended.

💡 Important: Note there is a unidirectional homing limitation, which can be critical on the elevation axis. The "home" command will always move in the counterclockwise direction towards zero. When power to the system is cycled, the gimbal will need to home in order to re-zero its position. Keep this in mind in the use case requires restricted travel limits, and homing would cause movement through an undesired region. Please make sure you have enough clearance around the gimbal to allow full 360° rotation of both axes to prevent damage to the surrounding area or your equipment.

Please see [Elevation Mount Home Position Angular 45 degree Offset](#) instructions for details.

💡 Important: To ensure cables do not become entangled during gimbal operation, connect power and data cables to only the bottom X-RST-E rotary stage. Power and communication is daisy-chained to the upper X-RST-E rotary stage through a slip ring.

Noise Emissions

The A-weighted emission sound pressure level (SPL) of this device does not exceed 70 dB(A) during intended use.



Specific items included with every system

- 1X Optional 4 conductor cable with 2 A signal wire flying leads and a grommet
- 1X Precision 2" alignment pin for optional angular offset realignment of the elevation apparatus with 2X low-profile M6 x 08 mm screws
- 4X M6 x 14 mm screws for bolting gimbal system to a mount surface

To set up your gimbal for safe operation, complete the following steps. Contact [Zaber Customer Support](#) at any time for clarification or additional information.



Before powering up the gimbal secure it to a mount surface via provided 4X M6 screws using 5mm hex key. Max torque specs required 6 N-m.



Plug in Power Supply and circular M8 connector from X-USBDC cable into the bottom X-RST-E stage.



Connect other side of X-USBDC cable into computer's USB port.

To safely adjust the height of the crossmember plate, complete the following steps. Contact [Zaber Customer Support](#) at any time for clarification or additional information.



Use a 5 mm hex key to remove four M6 screws on the crossmember plate feet (two on each side)...



...with one hand while supporting the plate with the other hand.



Cautiously, slide the plate with feet down to the desired position. Ensure you keep the plate level as you lower it to avoid any binding.

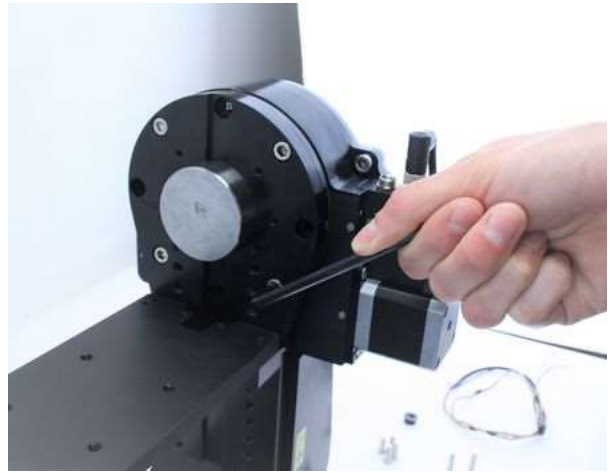


Secure the plate feet by hand tightening them to the elevation mounts. Tip: use foam from packaging as a support or to protect the gimbal arms from damage in case of accidental plate drop. Max torque for these screws is 4.2 N-m

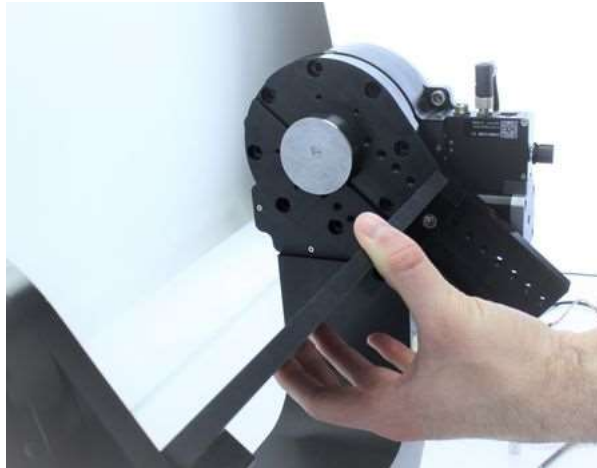
To physically offset the elevation mount home position on the gimbal, complete the following steps. Contact [Zaber Customer Support](#) at any time for clarification or additional information.



Insert 2" precision alignment pin into the elevation axis stage aperture. You may need to lower the crossmember plate to fully expose the aperture and alternative elevation mount holes.



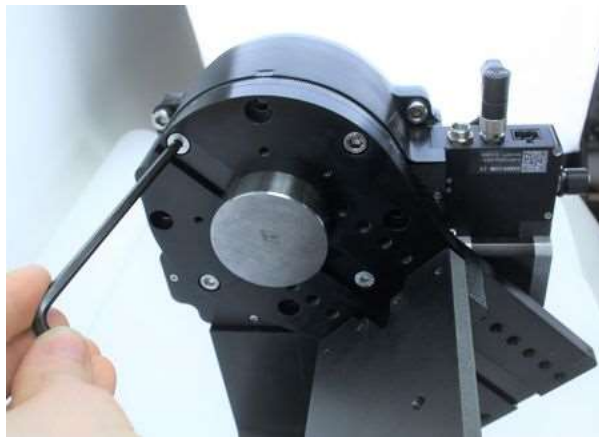
Use a 5 mm hex key to remove the four M6 screws.



Once all screws are removed, rotate the mount by 45°.



Re-fasten the four M6 screws to re-attach the mount.

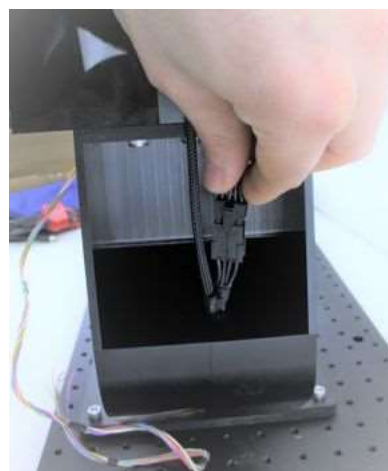


Ensure you use the two low profile M6 screws inside the key alignment feature to allow the crossmember plate to slide up to or past this height.
Note: Max torque for these screws is 4.2 N-m. Carefully, remove the alignment pin from the aperture.

Should you decide to use available 4X 2 Amp slip ring wire connections, to properly install the signal output cable complete the following steps. Contact [Zaber Customer Support](#) at any time for clarification or additional information.



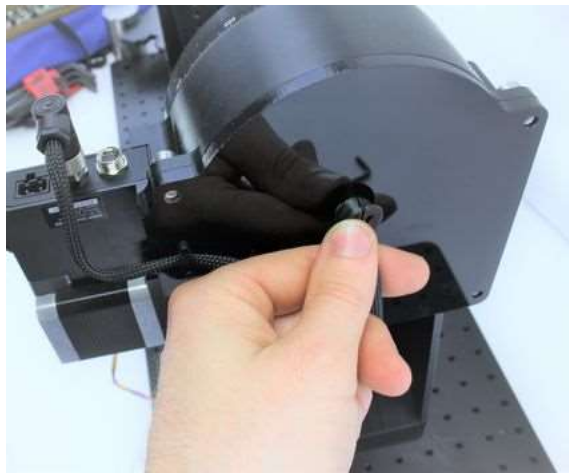
Insert the flying leads of the signal output cable through the back of the hole in the upper axis stage back plate.



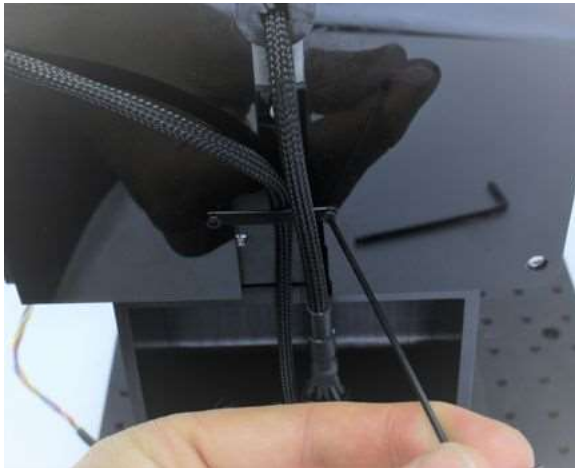
Plug the connector end into the mating connector inside the pocket of the gimbal arm, as shown. The connector should latch securely.



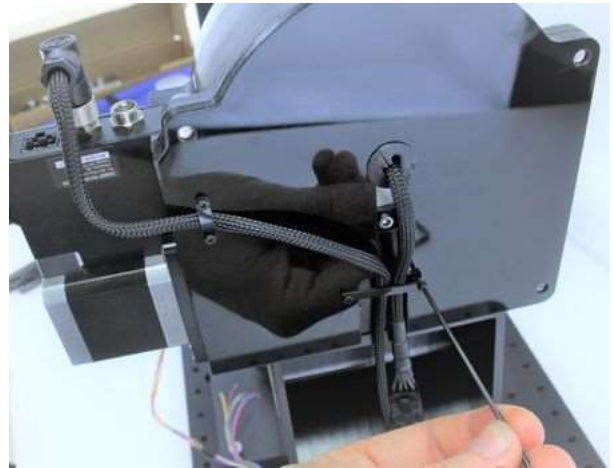
Pull the rubber grommet over the cable with the cutout facing upwards.



Press the grommet into the hole of the stage back plate.



Use a 1.5 mm hex key to remove the M2 screw on one side of the strain relief strap.



Use the strap to secure the cable and finger tight the M2 screw back..



Finished Signal Output Cable Installation.

- To control the motorized gimbal axes we recommend using [Zaber Console](#).

Motorized Axis Product Manual

The X-G-RST-E gimbals contain two separate X-RST-E rotary stages. Detailed information for controlling these devices, troubleshooting and more, can be found at the link provided below:

- [X-RST-E User Manual](#)

For Zaber's policies on warranty and repair, please refer to the [Ordering Policies](#).

Standard products

Standard products are any part numbers that do not contain the suffix ENG followed by a 4 digit number. Most, but not all, standard products are listed for sale on our website. All standard Zaber products are backed by a one-month satisfaction guarantee. If you are not satisfied with your purchase, we will refund your payment minus any shipping charges. Goods must be in brand new saleable condition with no marks. Zaber products are guaranteed for one year. During this period Zaber will repair any products with faults due to manufacturing defects, free of charge.

Custom products

Custom products are any part numbers containing the suffix ENG followed by a 4 digit number. Each of these products has been designed for a custom application for a particular customer. Custom products are guaranteed for one year, unless explicitly stated otherwise. During this period Zaber will repair any products with faults due to manufacturing defects, free of charge.

How to return products

Customers with devices in need of return or repair should contact Zaber to obtain an RMA form which must be filled out and sent back to us to receive an RMA number. The RMA form contains instructions for packing and returning the device. The specified RMA number must be included on the shipment to ensure timely processing.

If you would like to receive our periodic email newsletter including product updates and promotions, please sign up online at [www.zaber.com \(news section\)](http://www.zaber.com/news_section). Newsletters typically include a promotional offer worth at least \$100.

Contact Zaber Technologies Inc by any of the following methods:

Phone	1-604-569-3780 (direct) 1-888-276-8033 (toll free in North America)
Fax	1-604-648-8033
Mail	#2 - 605 West Kent Ave. N., Vancouver, British Columbia, Canada, V6P 6T7
Web	www.zaber.com
Email	Please visit our website for up to date email contact information.

The original instructions for this product are available at <https://www.zaber.com/manuals/X-G-RST-E>.

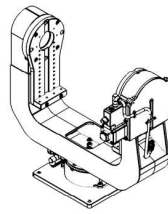
Please see [the Zaber Support Page](#) for default settings for this device.

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X-G-RST-E, X-G-RST-DE

Motorized Gimbal With Built-in Controllers,
Encoder And Slip-ring Wiring Options

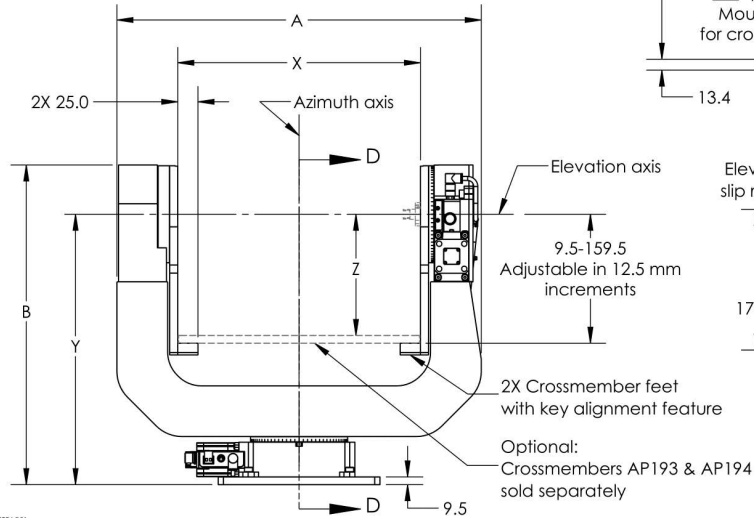
dimensions in mm



Model Number*	X	Y	Z	A	B	C
X-G-RST300-E03(SRxx)	300	334.5	0-175	450.4	395.5	273.2
X-G-RST500-E03(SRxx)	501.7	436.5	0-175	652.1	497.5	474.9
X-G-RST300-DE50(SRxx)	300	334.5	0-175	450.4	395.5	273.2
X-G-RST500-DE50(SRxx)	501.7	436.5	0-175	652.1	497.5	474.9

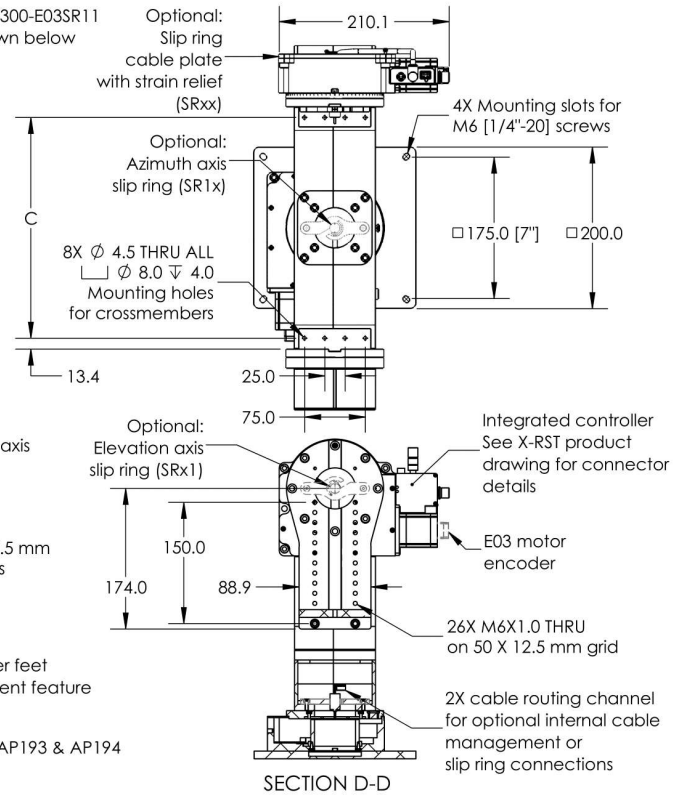
*See product page for complete list of available models at www.zaber.com

Please contact Sales Department for further inquiries



DWG 2304 R01

X-G-RST300-E03SR11
shown below



Specification	Value	Alternate Unit
<u>Microstep Size (Default Resolution)</u>	0.00015625°	2.727 µrad
<u>Built-in Controller</u>	Yes	
<u>Range</u>	360°	
<u>Accuracy (unidirectional)</u>	0.16°	2.792000 mrad
<u>Repeatability</u>	< 0.005°	< 0.087 mrad
<u>Backlash</u>	< 0.05°	< 0.873 mrad
<u>Maximum Speed</u>	24°/s	4 rpm
<u>Minimum Speed</u>	0.000095°/s	1.658 µrad/s
<u>Speed Resolution</u>	0.000095°/s	1.658 µrad/s
<u>Encoder Resolution</u>	200 CPR	800 states/rev
<u>Encoder Type</u>	Rotary quadrature encoder	
<u>Communication Interface</u>	RS-232	
<u>Communication Protocol</u>	Zaber ASCII (Default), Zaber Binary	
<u>Data Cable Connection</u>	Locking 4-pin M8	
<u>Maximum Continuous Torque</u>	1000 N-cm	1416.1 oz-in
<u>Maximum Centered Load</u>	150 N (See Spec Definition)	33.6 lb
<u>Maximum Cantilever Load</u>	2000 N-cm	2832.2 oz-in
<u>Aperture Diameter</u>	50.8 mm	2.000"
<u>Power Supply</u>	48 VDC	
<u>Power Plug</u>	2-pin Screw Terminal	
<u>Maximum Current Draw</u>	2200 mA	
<u>Angular Motion Per Motor Rev</u>	2°	

Specification	Value	Alternate Unit
Motor Steps Per Rev	200	
Motor Type	Stepper (2 phase)	
Motor Rated Current	1500 mA/phase	
Inductance	6.6 mH/phase	
Default Resolution	1/64 of a step	
Maximum Angular Momentum	0.4 kg·m ² /s	
Mechanical Drive System	Precision Worm Gear	
Limit or Home Sensing	Magnetic home sensor	
Gear Ratio	180:1	
Manual Control	Yes	
Operating Temperature Range	0-50 °C	
RoHS Compliant	Yes	
CE Compliant	Yes	
Vacuum Compatible	No	

Comparison

Part Number	Weight
X-G-RST300-E03SR10	13.2 kg (29.101 lb)
X-G-RST500-E03SR10	13.8 kg (30.424 lb)

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